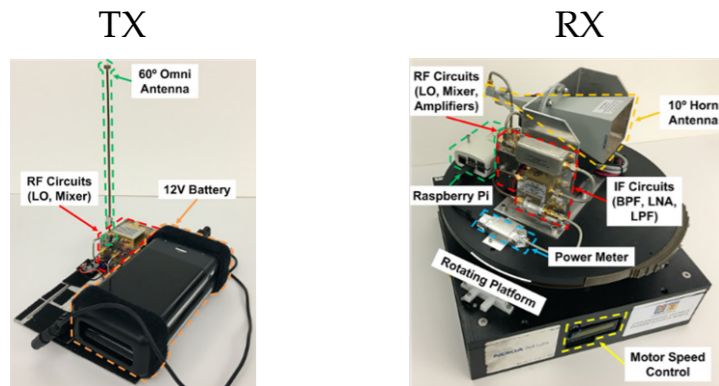


Abstract

- Within Beyond-5G and 6G wireless networks, Joint Communications and Sensing (JCAS) will allow small cells to perform sensing in addition to their traditional communication responsibilities.
- We model indoor and outdoor clutter using a portable 28 GHz mmWave channel sounder traditionally used for propagation modeling in communication [1-3].
- We collect 2,872,800 individual backscatter measurements in NYC and show preliminary results for JCAS clutter modeling and vehicle detection.

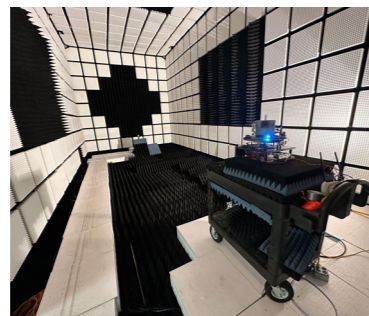
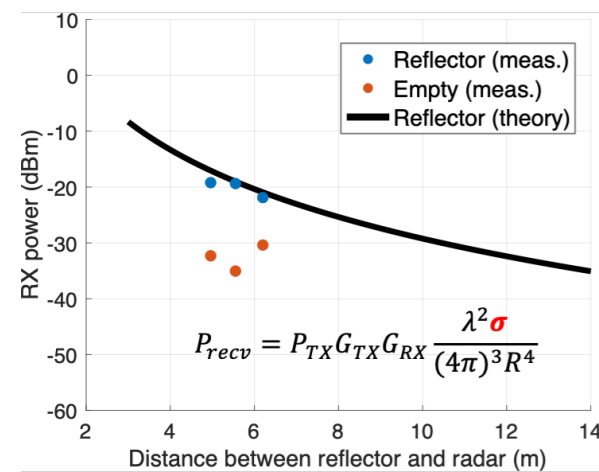
JCAS Measurement Platform

- We use a portable 28 GHz omni antenna transmitter and 10-degree receiver developed by Nokia Bell Labs and Universidad Técnica Federico Santa María.



Rigorous Calibration

- Reflector (meas.) is within 1.4 dB of reflector (theory).
- Known reflector RCS of 0.13 m² at 28 GHz [4].



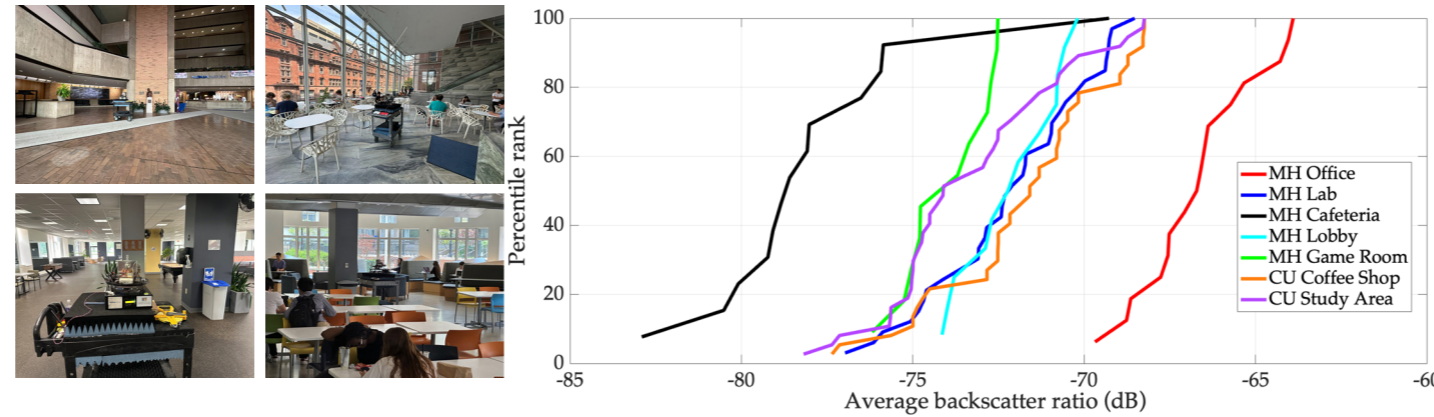
Static Clutter Statistical Model

- Obtain directional backscattered power across 360 degrees from several street intersections and calculate the statistical average.
- Representation of power variation across azimuth.



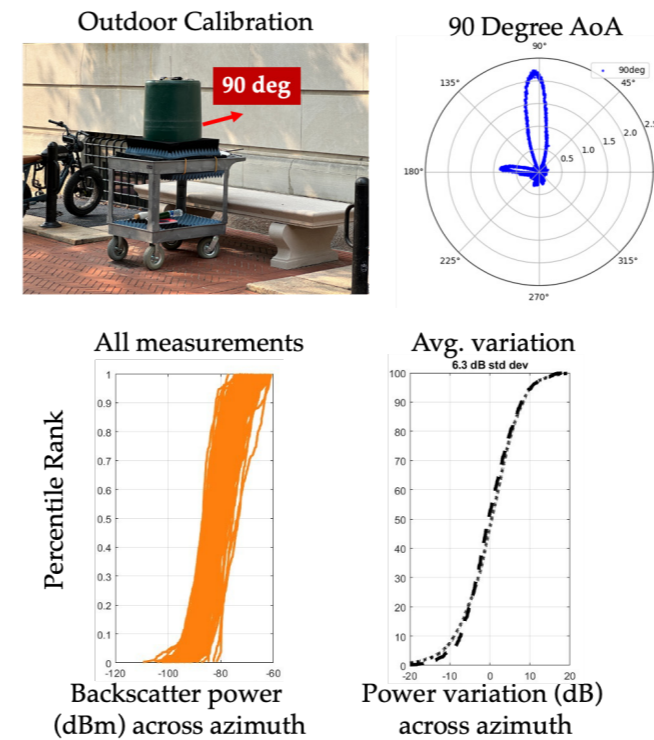
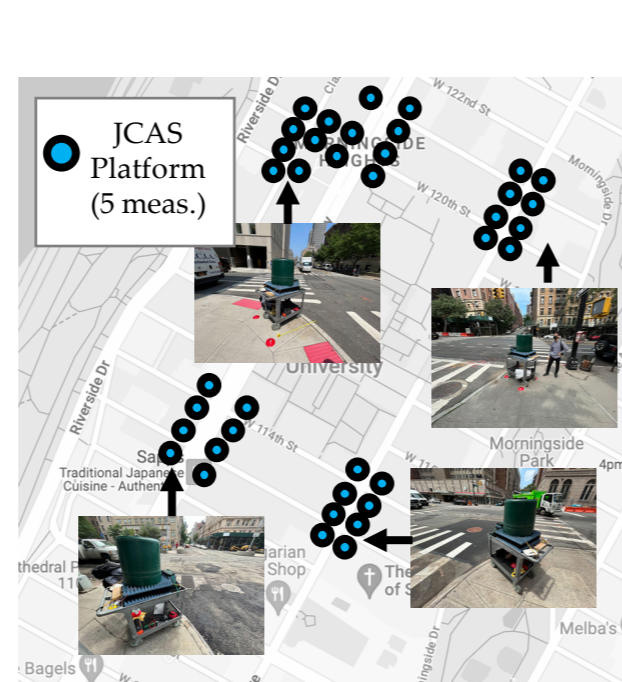
Indoor Backscatter Measurements

- Statistical models confirm that higher average backscatter is characteristic of smaller rooms, with larger rooms exhibiting lower backscatter.



Outdoor Backscatter Measurements

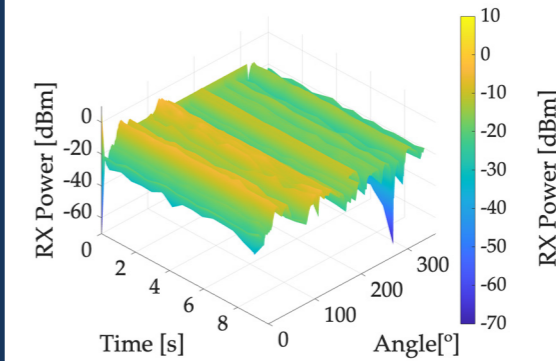
- Using the COSMOS FCC Innovation Zone [5], we collect 2,872,800 individual backscatter measurements in 190 locations spanning 10 intersections in NYC.
- We obtain a static clutter model for avg. power variation across azimuth.



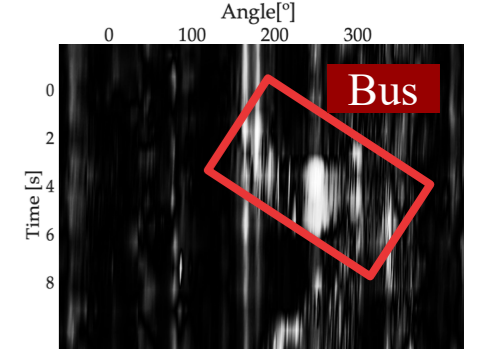
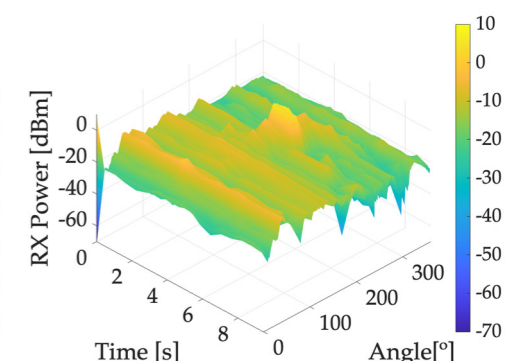
Vehicle Detection

- We placed the channel sounder, Tx elevated above the Rx, at street intersection corners. From there, we took a series of 22 10-second measurement samples. We recorded accompanying video footage to compare with the measurements.

Empty Measurement



Vehicle Measurement



Future Work

- We are beginning work on using the JCAS measurement platform for traffic monitoring, pedestrian detection, and integration with Lidar sensors for multi modal sensing.



Traffic Density Comparison



Pedestrian Detection



Lidar-Informed Modeling

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- [4] Reflector Datasheet: <https://sftp.eravant.com/content/datasheets/SAJ-024-S1.pdf>
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